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Chairman's Message:



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John P. Bussel, F.ACI, HoF.ACMA

n behalf of myself and the SPE Composites Division Board of Directors, welcome to the second newsletter of 2022. The past 2 years have been unusual and difficult for many of us as we deal with the COVID-19 pandemic. Many of us have not traveled, but instead, have spent countless hours in virtual meetings. Based on current trends, 2022 might be the year to return back to our business and professional lives that we used to know before the pandemic.

The SPE Composites Division Board, like most of us, carefully planned the Divisions activities and budgets to align with how the composites professional community was going to respond. Over the past few years we have supported technical programming for SPE ANTEC and Automotive Composites Conference and Exposition (ACCE). We look forward to increasing our efforts in FY23 to not only focus on ANTEC and ACCE, but to also celebrate new opportunities and most importantly our future.

One of the items the Board of Directors will be focusing on is solicitation of scholarships applications. The Dr. Jackie Rehkopf Scholarship is awarded to full-time graduate students with a focus on research activities targeted at ground transportation composite technology. Although the preference is given to female students, the best candidate will be selected. If no graduate students qualify then two \$2,500 scholarships may be awarded to undergraduate students with junior or senior standing. Then there is also the Harold Giles Composites Division Scholarship which is awarded to One undergraduate and one graduate student. An essay is required documenting experience in the composites industry including courses taken, research conducted, or jobs held. Lastly, there is the Automotive and Composites Conference & Exhibition (ACCE) Scholarship where two scholarships are awarded to full-time graduate students, one graduate or undergraduate junior or senior. Students must be in good standing and pursuing a degree in Polymer Science, Composites, Plastics or a related engineering discipline. A two-page essay is required showing planned work and how it will benefit composites in an automotive or other ground transportation application. One recommendation must come from the student's advisor or mentor. Scholarship recipients are required to present their research project at the next ACCE conference. We hope this year will encourage many applications. We can use your help and get the word out to people you know and encourage them to submit.

The Composites Division Board will be working to develop strategic goals and plan to provide members with personal value to help them grow in the composites industry and in the profession. One of the ideas is to have periodic presentations of composites applications and

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Chairman's Message continued...



field studies to learn about material advancements, manufacturing, and case studies of how composites are used. Be on the lookout for future updates as this idea is developed into practice.

Giving back – how can the Division members give back to the profession. One of the opportunities is to get involved on the Board. In late May we will be conducting elections for new Board members. If you are interested in steering the direction of the Composites Division or wish to champion a project that you are passionate about to help others in the composites community, we would encourage you to join the Board. If you are interested or would like to discuss your interests, please contact me at jbusel@ acmanet.org.

Lastly, the Composites Division Board of Directors thanks our newsletter sponsors for their support in these difficult times. We also thank the membership, for your support and dedication to the profession. We have so much to accomplish together. I look forward to working with you and guiding initiatives in the Division to meet your needs. Kind Regards,

John P. Busel, F.ACI, HoF.ACMA Chairman, Composites Division



A member of C ALTANA



Tribute to Cedric Anthony Ball



Cedric Anthony Ball

An Automotive and Composites Industry Champion, Leading Volunteer and Dear Friend

While the additional of the second state of th



enthusiast. He was preceded in death by his father, Anthony Ball. He is survived by his wife of 27 years, Libby J. Spaulding Ball; his children, Lisanne, Olivia and Donovan; his mother, Jean Cates Ball; and his sisters, Arlis Ball and Lorinne Ellis.

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Tribute to Cedric Anthony Ball continued...



Cedric Ball established an outstanding global career as Innovation, Marketing and New Business development leader in composite materials with in depth knowledge of the automotive, wind energy and building materials markets. Cedric began his career with General Motors as a chassis systems release engineer on the first-generation Saturn vehicle program. Since that time, he has served in a variety of marketing and new business development roles at Owens Corning. Ashland Performance Materials. BMC Inc. and Hexion Inc. He held a Bachelor of Science degree in General Engineering from the University of Illinois at Urbana-Champaign and co-MBA from Ecole des Hautes Etudes Commerciales (HEC Paris) and the Stephen M. Ross School of Business Administration at the University of Michigan - Ann Arbor. Cedric also was a certified 6 Sigma Black Belt.

As other achievements, we know Cedric from his role as Conference chairperson for SPE Annual Automotive Composites Conference and Exhibition 2009 and 2010. Cedric served several times as a board member in non-profit organizations, using his professional experience to set and deliver upon strategic plans, to the benefit of communities and people.

"Cedric was one of the finest gentlemen in the business and it was always my pleasure to work with him. I will miss him and so will the industry," – *Teri Chouinard, Intuit Group, Inc.*

"Cedric will be always remembered for his calm demeanor. He not only worked hard but worked with true commitment, team effort, heart in his projects. His ability to envision and communicate customer's unmet and unarticulated needs was second to none. He will be missed in the technical community by many,"

– Pritam Das, Toray Composite Materials America.

"It was my honor and pleasure to serve with Cedric on many SPE programs. His professional and personal support was well received and appreciated. I am saddened by his loss." – Fred Deans, Honored Service Member, SPE





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Tribute to Cedric Anthony Ball continued...



"I met Cedric in the late nineties when he worked for Owens Corning. We remained in touch for the following twenty-five years. Across my career in plastics, I have not met a person that exemplified the terms 'gentleman', 'businessman' and 'complete class act' more than Cedric. His work ethic was exceeded only by his integrity. His laugh was as heartfelt as it was contagious. I will deeply miss Cedric and offer my thoughts and prayers to his family."

– Len Nunnery, Plenco (Plastics Engineering Company)

"Cedric was one of those people who treated you as a friend from the first time you met him, and every time you crossed paths, he expressed genuine concern for how you were doing, before the topic changed to the business at hand. His contributions to the growth of the composites industry, and to the success of ACCE as contributor, sponsor and conference chair, are still accumulating and yet to be fully measured. I will miss his giant persona and salient insights."

- Dale Brosius, IACMI CEO & Chief Commericalization Officer "Cedric Ball was the consummate jack-of-alltrades. His strong technical background and business-oriented mindset meant that he was able to succeed in everything to which he set his mind. Cedric was known for his positive attitude and ability to bring people together. He always knew the best spot for dinner and was full of esoteric knowledge of every spot he visited. Vocation aside, Cedric was a personal friend to everyone he met. By taking personal interest in people's lives and with his diverse experiences was able to mentor and support budding talent like myself. I will sorely miss Cedric and grieve his death."

- Ian Swentek, Westlake's Epoxy Business (formerly Hexion Inc.)

"I actually met Cedric the first time face-toface in 2011 at ACCE in Novi where he joined our team. His involvement with the ACCE organization - as well SPE Composites division - was very clear from the start and has helped to put Hexion Westlake on the map. His commitment to growing this market was strong. More importantly, he was a trusted colleague and leader in many areas over his distinguished career. We are all better from knowing and working with Cedric."

- Francis Defoor, Westlake's Epoxy Business (formerly Hexion Inc.)

"We share the feeling of missing a much-valued person. Cedric's integrity, warmth and peopleoriented personality made it a pleasure to work together. He will be sorely missed, and our condolences go out to his family and friends."

 Sigrid ter Heide, Westlake's Epoxy Business (formerly Hexion Inc.)"

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ANTEC[®] 2022 **ANTEC 2022 WWW.4SPE.ORG/ANTEC22** June 14-16, 2022; Charlotte, NC

ANTEC® showcases the latest advances in industrial, national laboratory, and academic work. Papers will share findings in polymer research and/or new and improved products and technologies.

SPE is hosting ANTEC® 2022 in-person, colocated with PLASTEC® South, an Informa event, in Charlotte, NC, June 14-16. PLAS-TEC® South is a comprehensive annual plastic design and manufacturing event for plastics professionals, suppliers, and buyers to discover innovation, engineer new technology, and expand their networks. ANTEC® 2022 will also include an online component.

The presentations at the in-person event will be selected/invited based on the applicability of their topic across a wide cross-section of the plastics value chain. Presentation/ speaker selection, which will occur through a paper submission/review process and/or through invitation, will be considered based on the quality, relevance, and newness of any research done in the field as well as the speaker's position in the plastics industry. Technical Papers that are not selected for in-person ANTEC® will be recorded and delivered virtually over a schedule that will be announced soon.

The tentative schedule for in-person AN-TEC® 2022 is as follows:

Day 1 (June 14)

2:00 PM - 5:00 PM	SPE Leadership Meetings		
5:00 PM	General Reception with SPE Meetup Area		
Day 2 (June 15)			
8:00 AM - 12:00 PM	ANTEC® Sessions		
12:00 PM - 1:30 PM	SPE Honors & Awards Lunch		
1:30 PM - 5:00 PM	ANTEC® Sessions		
5:00 PM	SPE Chapter Networking Events		
Day 3 (June 16)			
8:00 AM - 12:00 PM	ANTEC® Sessions		
12:00 PM	Adjourn		

SAVE THE DATE: June 14-16, 2022

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Award Winning Paper

Toward Automated Foreign Object Detection Of Carbon Fiber Laminates Using Pulse Echo Ultrasound

Nathaniel J Blackman, David A Jack Baylor University, Waco, TX

Abstract

arbon fiber composites are becoming more desirable as a design choice in a wide range of industries due to their high strength to weight ratio. One common challenge to greater adoption of carbon fiber laminates is the reduction in performance due to the occurrence of foreign object defects introduced during the laminate manufacturing. These foreign objects lead to increased costs and waste through both the discarding of failed parts and in the need to overdesign parts to survive when foreign objects are not detected. The ability to reliably find foreign objects would lead to significant savings and would open the door to greater adoption of carbon fiber composites by making these parts cheaper, safer, and perhaps more lightweight. Nondestructive techniques are crucial to the detection of foreign objects, and ultrasound has shown to be a cost-effective and reliable technique for the identification of foreign objects. Previous work by Baylor researchers has shown the ability to determine the size and location of foreign objects made with Teflon films with high accuracy. This work focuses on the improvement of these methods and adapting them for other foreign object materials, specifically: copper, peel ply, infusion mesh, vacuum bagging, and gloving; while moving the technique towards full automated detection.

Background

Transportation industries are feeling significant pressure to improve fuel efficiencies and reduce emissions [1]. One solution to increasing efficiency is the reduction of weight. The greater adoption of composites presents the opportunity for light-weighting. Many composites have high strength to weight ratios, and carbon fiber laminates in particular have one of the highest strength to weight ratios making them a material desirable for use in structural applications [2].

There are several different manufacturing techniques for carbon fiber laminates [2], and many of these techniques require at least some manual process. This makes carbon fiber composites susceptible to manufacturing defects. Defects such as delaminations, improper lavup, inclusions etc. have been known to be caused due to faulty manufacturing techniques [3]. These defects can have a significant impact on the final part performance and increase the costs associated with using carbon fiber composites [4]. The true effects of these defects is the subject of ongoing research as researchers attempt to answer how different defects or induced damage impacts part performance through modeling [5–7] as well as experimentation [8]. This research will focus specifically on foreign objects which occur as excess material that ends up in the part during the manufacturing process.





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Award Winning Paper cont...

Along with the need to better understand the effect of defects on composite parts, there is a growing need for adequate testing of composites. Traditional testing techniques are destructive and can add significant cost to the use of composites. This creates a need for non-destructive testing (NDT) techniques to complement traditional testing and aid in part qualification.

Several NDT methods have been examined to determine their ability to find foreign objects within carbon fiber laminates. X-ray CT [9], acoustography [10], thermography [11], terahertz [12], and eddy current [13] techniques have all shown promise in their ability to identify foreign objects in laminated composites. Ultrasound is the most popular NDT method [14], in part due to its relative low-cost and ease of use in comparison with many other methods [3]. Several researchers have explored the use of ultrasound for the detection of ply orientation [15,16], adhesive thickness [17,18], detection of wrinkles [19,20], and damage [7,21,22] among other areas of concern in carbon fiber laminates.

Multiple researchers have investigated automated or semiautomated methods for detecting foreign objects in carbon fiber laminates. Benammar et al. [23] applied signal processing techniques to ultrasonic scan data to identify simulated delaminations. They found success in determining the depth of the simulated delamination, but report no findings on the ability to determine size and shape. Poudel et al. [24] and Barry et al. [25] separately both investigated the use of artificial neural networks (ANN) to detect foreign objects within composite laminates. Both researchers were able to demonstrate success in determining the presence of foreign objects but neither work focused on the quantifying the dimensions of the defects, limiting the ability to objectively compare results against their approach.

Recent work by Mohammadkhani et al. [26] presents the use of an algorithm to detect and characterize defects using a wavelet transform on the base signal. They make use of a 10 MHz phased array transducer to scan a part with 5 different materials used as foreign objects: Teflon, paper, release tape, bag tape, and peel ply. In their work, all objects were placed between the 8th and 9th plies of a carbon fiber composite. The reported error in the size estimation of Teflon, bag tape, and peel ply foreign objects was, respectively, -41.7%, 20%,

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and -66.7%. In absolute units, the errors are, respectively, 1.42 mm, 0.63mm, and 2.54 mm in capturing the effective width of the square objects. These results are highlighted as they are directly similar to the PTFE, vacuum bag, and peel ply foreign objects studied in the present work.

The recent work of Ma et al. [27] presents the use of a signal correlation algorithm to detect and size defects. They study intentional foreign objects made of graphite approximately 0.25 mm in thickness and with a diameter of 12.7 mm. They benchmark their algorithm against traditional phased array ultrasound and found they were able to size the height and width of the foreign objects accurately with an error ranging form 0.475 mm to 0.175 mm.



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In a work by the current authors [28], the detection of PTFE foreign objects within a carbon fiber laminate was studied. Twelve circular foreign objects 0.05 mm thick and with diameters of 12.7 mm 6.4mm, 3.2 mm and 1.6 mm were intentionally placed within twelve different laminates at the interfaces between the 3rd and 4th plies, the 6th and 7th plies, and the 9th and 10th plies. Edge detection was applied to all samples along with a smoothing filter and the magnitude of the gradient traced (MGT) was presented for the sizing of the foreign objects. The average absolute difference in the estimation for all foreign objects studied was 0.1 mm.

This work seeks to apply the techniques described in [28] to a carbon fiber composite part containing multiple types of foreign objects while simultaneously presenting improvements towards a more automated MGT method for the sizing of foreign objects. This work will focus on a woven carbon fiber part with six different foreign objects: copper, gloving, infusion mesh, peel ply, PTFE, and vacuum bagging. While the average absolute difference in estimating size is greater than what was observed in [28], the estimation of the area of the foreign objects still compares favorably to other methods in the literature when comparing materials like for like. Future research is needed to develop the method more fully for each of the foreign objects studied and is the topic of ongoing future work.

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Experimental Set-Up

Foreign Object Fabrication

Foreign objects were fabricated of six different thin materials: polytetrafluoroethylene (PTFE), vacuum bagging, copper film, infusion mesh, gloving, and peel ply. PTFE is a common material studied as a foreign object [26,28], copper film is likely to replicate the signal of an intentional foreign object such as embedded radar or lightning strike material, while the other objects are chosen as they are all common consumables used during the fabrication of the composite laminate. The PTFE foreign object is in the shape of an asterisk and was created using a Silhouette Cameo and measures 0.13 mm. The irregular shape of the asterisk is chosen to determine the ability to identify the shape of foreign objects with multiple sharp corners and a more irregular shape. The other foreign objects were not easily cut using the Cameo's preset cutting settings and were cut with scissors to be nominally 6.4 mm x 6.4 mm (1/4" x1/4").

After fabrication, and prior to placing the foreign objects in the carbon fiber composite all foreign objects were imaged with a Keyence VR3000 to determine their true size. Although the foreign objects are de-

signed to be rectangular, there was some irregularity in their shape. The height and width are defined as the maximum distance between the nominally parallel edges. The height and width are multiplied together to create an effective area. This effective area is then compared with the true surface area measurement taken by the Keyence, based on the measured profile of each foreign object as it is imaged and profiled. The effective area for the asterisk shaped PTFE object is calculated differently than the other objects and is computed by fitting a circle to the outer points of the asterisk shape. Then, the area of the eight triangular cutaways is subtracted by measuring the interior angle of each cutaway and the distance between the center of the fitted circle and the vertex of the cutaway. Table I summarizes the measurements taken for each object. Of note is the discrepancy between the effective and surface area measurements for the Infusion Mesh object which is shown in Figure 1. This is due to the nature of the infusion mesh which has significant spatial gaps between the plastic material which are not measured as part of the surface area of the foreign object. For the infusion mesh, the effective area measurement includes the open gaps, while the surface area measurement includes only the material.

Table I: Summary of Foreign Object Measurements using Microscopy

Material	Height (mm)	Width (mm)	Effective Area (mm²)	Surface Area (mm ²)
Copper	7.04	6.94	48.84	50.48
Glove	8.44	8.06	68.02	65.05
Infusion Mesh	7.69	6.74	51.82	16.01
Peel Ply	9.26	7.29	67.48	71.19
PTFE	12.42	12.42	96.51	93.63
Vacuum Bag	7.47	4.84	36.12	36.48

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Figure 1: Image of Infusion Mesh taken with Keyence VR 3000

Composite Fabrication

A laminated composite of nominally 127 mm x 178 mm (5" x 7") was manufactured using the VARTM method. A 6 oz., 3k tow, plain weave fabric from ACP Composites was used. The composite is comprised of twelve lamina with a layup of [0/45/0]₄ where the foreign objects were placed between the sixth and seventh plies. Proset INF 114 resin with Proset 211 hardener was chosen as the resin-hardener combo for the infusion process, and the composite was cured according to the manufacturer's recommendations. Figure 2 shows the placement of each foreign object during the manufacturing of the part. During the layup process, all foreign objects were placed between the sixth and seventh plies at the midplane of the composite. The composite being studied did exhibit some surface porosity post-cure, but that occurs in regions other than those where the placed foreign objects are placed and as such do not impact the analysis.

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Figure 2: Diagram showing the location of foreign objects in the composite laminate when viewed from the tool side

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Ultrasonic Scanning Setup

The part was scanned using the custom immersion scanning system as shown in Figure 3. A 10 MHz spherically focused transducer from Olympus was used to scan the composite in a pulseecho mode. The ultrasonic parameters were controlled using an Olympus Focus PX. Positioning of the motors was controlled using Velmex VXM motor controllers to move two axes made up of Velmex BiSlide positioning systems. A custom MATLAB program is used to create a raster path, and send commands to the motor controller. The scan discussed in this work covers a scan region of 80 mm x 130 mm with a spacing of 0.2 mm between scans. A magnetic linear encoder reads the position of the ultrasonic transducer and the Focus PX acquires data over the scanning region. Upon completion of the scan, the data is exported to MATLAB where it is analyzed using a custom in-house code discussed below.

Figure 3: (a) Picture of the custom immersion C-Scan System used in this study. (b) Diagram of the experimental setup for scanning the composites





Analysis

Determination of Lamina Count using A-scans

During the scanning process, a-scans are collected at the designated locations by the pulserreceiver. These a-scans represent the voltage created by the displacement of the piezoelectric material in the transducer across time. The entirety of the ultrasonic dataset will be represented as $F(x_{1,k}, x_{2,i}, t)$, which represents the received ultrasonic amplitude at a specific time t, at the kth location in x_1 where k is of the set $k = 1, 2, ... N_1$, and the lth location in x_2 where l is of the set $l = 1, 2, ... N_2$.

Prior to analyzing the data, all a-scans are fed into an algorithm that fits the signal response from the front wall of the composite to a two-dimensional 3rd order plane. This plane is then used to adjust each a-scan such that the occurrence of the front wall occurs at the same adjusted point in time \tilde{t} , where \tilde{t} $= t - t_0$. This algorithm is designed to identify the detection threshold which creates the optimal fit plane to the data. This optimal fit is defined as the threshold at which the value of the 3rd peak in the average of all shifted scans is highest, and the shifted dataset is defined as $F(x_{1\kappa}x_{2}, \tilde{t})$. Once the dataset has been shifted, a gaussian smoothing filter is applied to $F(x_{1\kappa}x_{2\mu}t)$ as is described in [28], and the shifted and smoothed dataset is then defined as $\tilde{F}(x_{1\kappa}x_{2\tau}\tilde{t})$ where the time \tilde{t} represents the shifted time to align all data to the front surface of the part and \tilde{F} represents the regionally smoothed data.

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Figure 4: (a) Average A-scan for the composite part (b) A-Scans over the different defective regions compared with the average a-scan where the front wall echo is marked with a dotted line and the back wall echo is marked by a dashed line. Note the reflections due to the foreign objects can be observed at approximately 0.9 µs.

Figure 4(a) shows the averaged a-scan for

the composite after shifting the data in

time. This is the average a-scan over the en-

tire region of the part scanned and includes

regions without FOD and with FOD. Figure

4(b) is provided to show an example of the ultrasonic wave generated when scanning a

region of the composite containing any of

the six foreign objects used and comparing

it with the averaged a-scan across the laminate. Five of the six foreign objects cause an appreciable change in the ultrasonic waveform with only the infusion mesh foreign object not creating a significant response. It

should be noted that there is no significant

indication of the presence of foreign objects

in the averaged a-scan.



In order to determine the ply interface estimates, shown as the red circles in Figure 4(a), the back wall of the part is first identified, which occurs at approximately 1.8 µs. The number of plies is then determined by the distance in time between the front wall and the back divided by the nominal thickness of an individual ply. The total thickness of the part is identified using the equation:

$$d = \frac{t c}{2}$$

where *d* is the thickness of the part, *t* is the time between the front and back wall echoes, and c is the speed of sound of the material. The carbon fiber material used for this experiment has an measured thickness of 0.23 mm for each lamina prior to manufacturing. Equation 1 can be adapted to identify the estimated time of flight of an individual lamina as $t_{lamina} = 2 d_{lamina}/c$ yielding the time to pass through one lamina can be determined as approximately 15.24 µs for an estimated speed of sound of 3000 m/s. Using this value in Equation 1 for the measured total time of flight, there are estimated to be 11.88 plies in the composite. This is rounded to the nearest whole number correctly identifying the composite contains 12 plies. The ply interfaces are then giving pre-seeded initial locations for the ply interfaces. The first ply interface is given an initial guess of 35 percent of the 15.24 µs for the ultrasonic wave to pass through one lamina from the front wall and each successive guess is assumed to take the full 15.24 µs. The software then determines the nearest minima to each initial guess as the location of the ply interface.

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Foreign Object Depth using B-scans

B-scans are another common way to visualize and present ultrasonic scan data. A traditional b-scan often shows the ultrasonic response as a function of time and one scan dimension. For example, a traditional b-scan would show all the a-scans stacked together taken across the x, dimension at a fixed point in x_2 . While this is a useful tool for examining many a-scans at once, in the present context there is an extension of the standard technique for identifying foreign objects. Specifically, the b-scan is plotted with a maximum criterion for each point in time and space. Figure 5 presents such bscans where both the x_1 (left) and x_2 (right) directions are held constant as described by

$$\check{F}(x_{1,k},\tilde{t}) = \max_{x_{2,l} \in \{x_{2,0}, x_{2,N_2}\}} (\tilde{F}(x_{1,k}, x_{2,l}, \tilde{t}))$$

and

$$\check{F}(x_{2,l}, \tilde{t}) = \max_{x_{1,k} \in \{x_{1,0}, x_{1,N_1}\}} (\tilde{F}(x_{1,k}, x_{2,l}, \tilde{t}))$$

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As can be seen in Figure 5, this is effective at quickly identifying the presence and depth of foreign objects. In these images, the locations of the calculated ply interfaces from Equation I are superimposed as black dotted lines except for the sixth ply interface which is highlighted and plotted as a white dotted line. The initial reflection of the ultrasonic waves from the foreign objects can be seen occurring after the sixth lamina and just before the seventh lamina as the part in agreement with the part that was manufactured. It should also be noted some of the foreign objects created additional echoes that can be seen as bright reflections between the seventh and eight ply locations, thus only the first indicator should be used in the analysis to avoid false positives.

Figure 5: B-scans along both the index (left) and scan (right) directions plotted with a maximum criterion. Dashed Lines are overlayed at the minima before each laminar reflection. The dashed line in white highlights the sixth lamina. Color represents the normalized magnitude of the ultrasonic response.



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Further work must be done to improve the automation of determining the occurrence of foreign objects in the b-scan. One method that has been briefly investigated is to tabulate the maximum amplitude of the signal received between lamina and plot the resulting histogram of the tabulated data. Figure 6 shows the histogram of the gated maximum value of the ultrasonic signal for a gate spanning the third and fourth plies (Figure 6 a) and for a gate spanning the sixth and seventh plies (Figure 6b). It is apparent that there is a significant difference between the two gated significant difference between

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nals. or the case of the gated signal between the third and fourth plies the resulting signal amplitudes at each spatial location are tightly grouped and the median and mean are nearly equal. Conversely, the distribution of the amplitudes of the gated signal between the sixth and seventh laminate is much different. In this region, the region encompassing the foreign objects, there is a significant difference between the mean and the median of the gated signal amplitudes. This is due to the high signal return caused by the foreign objects. This approach may be useful to helping an operator determine the presence and depth of foreign objects, but is sensitive to the overall size of the part scanned relative to the size of the foreign objects and must be used with caution.

Figure 6: Histogram of the gated signal amplitude from each spatial location (a) between the 3rd and 4th plies and (b) between the 6th and 7th plies, the latter of which is where the foreign objects occur



Use of C-Scans to Identify Area and Size

The use of a-scans and b-scans are appropriate for determining, respectively, the presence of foreign objects and the depth at which they are located. In the following section c-scans will be shown to quantify the size and shape of defects within the composite. C-scans represent the ultrasonic intensity at each point in space across x_1 and x_2 at a single instance in time or over a gated range of times. Taking the amplitudes at a single point in time is highly sensitive to determining the correct depth and is dependent on a highly homogenized material and highly trained technician. The present work focuses on the inspection of plain-weave carbon fiber laminates whose acoustic behavior is inhomogeneous and aims to simplify the art of foreign object detection to the point of semi or full automation. This makes it more practical to gate cscans over a longer region of time, reducing the sensitivity of the methods and uses the same criterion as described in [28],

$$\check{F}(x_{2,l}, \tilde{t}) = \max_{x_{1,k} \in \{x_{1,0}, x_{1,N_1}\}} (\tilde{F}(x_{1,k}, x_{2,l}, \tilde{t}))$$

Using the information gained from the b-scan images, \tilde{t}_m is defined as the instant in time when the signal from the sixth ply interface is captured and \tilde{t}_n is defined as the instant in time when the signal is captured from the seventh ply interface.

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Figure 7: C Scan plotting the maximum normalized amplitude between the sixth and seventh plies.

clearly identifiable. Based on the representative a-scans shown in Figure 5(b), it is not a surprise that the infusion mesh cannot be found. The infusion mesh can be observed in the top right region of the c-scan, but appears as a ghost image that could in other cases be a false positive. This feature is left for discussion in Figure 8. The shape of the remaining foreign objects presented in the c-scan roughly matches the true shape of each foreign object. The angle and projections present in the asterisk shape of the PTFE foreign object are not well defined, but the other four objects appear as roughly rectangular just as they were fabricated.

In order to quantify the shape of the identified foreign objects, the use of an edge detection technique is needed. The magnitude of the gradient is a simple method commonly used in image processing [29] that can be easily applied to the ultrasonic data. A high order central difference method (see e.g., [30]) is applied to the data to calculate the partial derivatives in both the x_1 and x_2 directions. The magnitude is then calculated as the sum of the squares of the partial derivates as shown

$$\check{F}(x_{2,l}, \tilde{t}) = \max_{x_{1,k} \in \{x_{1,0}, x_{1,N_1}\}} (\tilde{F}(x_{1,k}, x_{2,l}, \tilde{t}))$$

The MGT method, as presented by the current authors in [28], traces along the bounded maxima of the gradient to determine the size of the foreign objects. No shape is superimposed, and the trace follows the maximum surface around the boundary of the object. When no obvious maximum is available, the method takes the center value of the gradient along a single projection as the peak. Figure 9 shows the modified c-scan image created by calculating the magnitude of the spatial gradient of the c-scan.

In order to identify the size of the infusion mesh an alternative method must be employed. The reflection of the back wall is reduced in the region of the infusion mesh foreign object due to significant attenuation around the infusion mesh as can be observed in Figure 5(b). Thus, viewing the amplitudes across the back wall reveals the location and size of the infusion mesh foreign object as shown in Figure 8. Similar to the previous approach, the magnitude of the gradient is applied to the data to determine the edges of the Infusion Mesh.

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Table II presents the spatial measurements obtained from the above analysis of the ultrasonic waveforms for each of the foreign objects in the composite. The height and width of the foreign objects is taken as the maximum difference in the x_1 and x_2 directions. The greater measurement is always assumed to be the height to account for any accidental rotations of the object during the manufacturing process. The absolute difference is defined as

 $\varepsilon = abs(s_{true} - s_{meas})$

where s is the respective dimension, specifically height or width, being compared. The absolute percent error is defined as

$$\varepsilon = \frac{abs(A_{True} - A_{meas})}{A_{True}}$$

The area for each foreign object is compared with the surface area measurement from the Keyence with the exception of the infusion mesh which is compared to an estimated

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Material	Height (mm)	Absolute Difference (mm)	Width (mm)	Absolute Difference (mm)	Surface Area (mm²)	Absolute Percent Error (%)
Copper	7.87	0.83	7.76	0.82	55.03	9%
Glove	8.10	0.34	7.50	0.56	55.43	15%
Infusion Mesh	8.97	1.28	8.37	1.63	55.68	7%
Peel Ply	8.45	0.81	7.99	0.71	51.38	28%
PTFE	10.70	1.72	9.70	2.72	68.27	27%
Vacuum Bag	8.54	1.07	5.87	1.03	40.86	12%

Table II: Ultrasonic Measurement of each foreign object using Magnitude of Gradient

area value. For comparison, in the work by Mohammadkhani et al [26], the error in estimating the size of PTFE, bag tape, and peel ply, all measuring 6 mm x 6 mm, using their automated technique are 43.8%, 20%, and -66.7%. It assumed that the bag tape discussed is similar to the vacuum bagging studied in the present work. The results in Table II are significant in that for each of the comparisons that can be made to published

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data, the MGT method shows a significant improvement in all but the PTFE foreign object studied here which is of a more complex geometry than other similar works. This is more significant as the sample studied in the present work has more internal reflections to add noise to the signal. These internal reflections are caused by the woven laminate studied, whereas previously published work focused on unidirectional laminates which have much cleaner acoustic signals aiding in the analysis of the captured waveform.

It should be noted that the composite being studied had noticeable amounts of surface porosity. It is reasonable to expect this surface porosity to negatively impact the ability of the ultrasonic waves to predictably propagate through the composite and is likely the cause of greater error in measurements around the foreign objects which disrupt the flow of the resin during the VARTM process and are likely to be areas with greater porosity.

In order to simplify and improve the detection of the foreign objects in the c-scan, the intensities of $\hat{F}(x_{1,\kappa}, x_{2,\iota})$ were modified to highlight signals likely to be caused by the foreign objects. This was done by determining all amplitudes in \hat{F} greater than 3 standard deviations above the median signal in the dataset. All signals above this thresh-

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old were set to 1 in the normalized dataset with the remaining amplitudes left at their current values. Figure 10 shows the results of this modification which more distinctly highlights the foreign objects. As with the original c-scan, the gradient of this dataset is calculated and used to determine the edges of each foreign object as shown in Figure 11. The forcing of the signals above the threshold to 1 creates a distinct and obvious boundary of the gradient that is easily traced to determine the size of each object. Table III shows the results of the measurements taken of the new dataset. In general, the absolute difference in determining the height and width of the foreign objects decreased. The error in calculating the area increased for the copper and gloving foreign objects, while the error for the PTFE and vacuum bag foreign objects decreased dramatically. This new method was still unable to detect the infusion mesh object. Because of this the measurements belonging to the infusion mesh row are left blank.

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Material	Height (mm)	Absolute Difference (mm)	Width (mm)	Absolute Difference (mm)	Surface Area (mm²)	Absolute Percent Error (%)
Copper	7.21	0.17	6.81	0.13	38.41	24%
Glove	8.32	0.12	7.76	0.30	48.24	26%
Infusion Mesh						
Peel Ply	9.49	0.23	7.87	0.59	52.69	26%
PTFE	11.70	0.72	11.65	0.77	97.09	4%
Vacuum Bag	7.71	0.24	5.09	0.25	33.63	8%

 Table III: Ultrasonic Measurement of each foreign object using Magnitude of Gradient post

 modification based on histogram

Summary and Next Steps

This paper presents the use of the MGT method and other detection algorithms for the detection of foreign objects in carbon fiber laminates. A carbon fiber laminate was fabricated with six different materials intentionally placed within the part as foreign objects. A systematic approach for locating and finding the foreign objects is demonstrated using a-scan, b-scan, and c-scans analyses. Five of the six materials were successfully detected at the spatial and depth location at which they were fabricated. Conversely, the depth of the infusion mesh object can not be determined using the analysis techniques presented, but the feature can be detected and the spatial dimensions can be quantified. An improvement on the application of the c-scan and application of the gradient as compared with previously published results is also presented that provides higher contrast in defining the foreign objects as well as a more defined gradient. In addition, the MGT was found to be considerably more accurate in the sizing of foreign objects than other recent works when controlling for the material being studied.

This work directly benefits any industry that makes use of laminated carbon fiber composites as the foreign objects significantly impact the performance of these composites. The ability to reliably detect and quantify foreign objects will lead to greater safety in composites and reduce the need for overdesigning of composite parts. Future work will study each of the foreign objects in greater depth and apply the methods presented across a greater number of samples. While the method presented has components of the analysis that are at automated (e.g. the detection of layers, and preprocessing of the normalized c-scan of the magnitude of the gradient), there is still work needed to tie the different components of the analysis together in a cohesive manner and limit the need for human interpretation.

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Councilor Report

By: Dale Brosius

April 15, 2022

meeting of the SPE Council was held on March 30. The main purpose was to communicate key initiatives from the executive committee and report on the financial position of SPE.

Regarding finances, the position of SPE has improved greatly over the last several years. Both revenues and expenses were down in 2020 and 2021 due to the preponderance of virtual events. The operating results, however, are showing improvement. Operating profit over the two years was \$359,000 and investment income was \$1,237,000. The Society is forecasting a slight loss for 2022 as the industry returns to in-person events and attendance is not expected to return fully to pre-pandemic levels in 2022.

SPE HQ staff has completed the exit of the physical space in Danbury and all employees are working remotely with occasional inperson meetings. This is saving the Society roughly \$150,000 per year in operating costs

The SPE Foundation awarded \$202,850 in scholarships in 2021 to 51 students at 31 universities. This includes Composites Division scholarships of \$14,000 to five students.

President-Elect Bruce Mulholland presented the status update to the 2021-2022 strategic plan. Emphasis is on improving opportunities for networking and knowledge. Some highlights include:

- Honored Service Members and Fellows of the Society have been granted lifetime membership in SPE.
- Part-time students enrolled in a degree program related to plastics are now able to receive free student membership. Previously, only full time students could do so.
- SPE hosted a Diversity, Equity and Inclusion (DEI) conference in January 2022 with 103 participants and archived on-line available to SPE members.
- The Plastics in Aerospace conference held virtually in 2021 will transition to an inperson conference in November 2022 in Phoenix, AZ
- ANTEC returns as an in-person event in June 2022, including both technical and non-technical content aimed at attracting a wide base of the industry and increasing networking opportunities.
- A new parts competition to replace the Plastics for Life competition will be announced at ANTEC 2022.





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